

Kokkos-HClib: enabling high-performance and resiliency for HPC systems

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Kokkos

□ What's Kokkos?

- Kokkos enables single performance portable codes
 - ✓ CPUs, NVIDIA GPUs, ...
- Kokkos provides data abstractions critical for performance portability not available in OpenMP or OpenACC (Kokkos::View)
- Essential parallel constructs
 - ✓ Kokkos::parallel_for();
 - ✓ Kokkos::parallel_reduce();
 - ✓ Kokkos::parallel_scan();



Kokkos Example

```
1  View<int*> x("x", N); // Construct a View (length: N)
2  // Parallel For
3  parallel_for(RangePolicy<>(0, N), // 1D Range (0 to N)
4              [=] (int i) { // C++11 lambda
5                  x(i) = i; // Computational Body
6              });
7
8  int result = 0;
9  // Parallel Reduce
10 parallel_reduce(RangePolicy<>(0, N), // 1D Range (0 to N)
11                [=] (int i, int &update) { // C++11 lambda
12                    update += x(i); // Computational Body
13                }, result); // Value to update
14 std::cout << result << std::endl;
```



Enabling Resiliency in Kokkos

□ Motivation

- Failure probability “significantly” increases as the number of nodes increases [1]

□ Observation

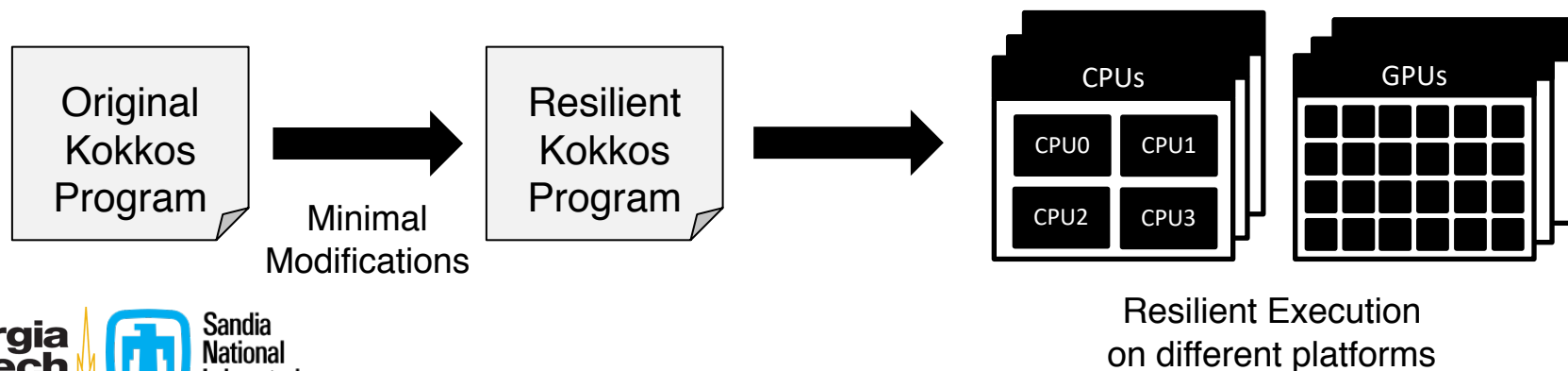
- User-level failure mitigation mechanisms will become more important in the next generation systems
 - ✓ Checkpoint/Restart (C/R)
 - ✓ Task Replay
 - ✓ Task Replication
 - ✓ Algorithm-based Fault Tolerance (ABFT)



Enabling Resiliency in Kokkos

□ Research Question

- When enabling resiliency in Kokkos, what is a desirable point in the performance-portability-productivity (P3) space?
- What is a desirable user-facing parallel-resilience API that enables good productivity-portability?



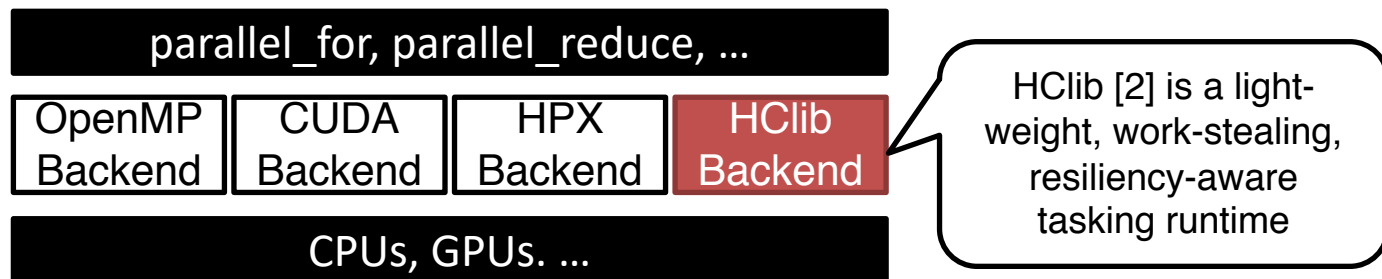
Resilient Kokkos

□ Overview

- Provides Kokkos with resilient execution capability
- Build on top of Resilient HClib [2]
 - ✓ Provides various runtime APIs for task-level resiliency

□ Our Current Focus

- Implementation of Kokkos-HClib Backend
- Design and implementation of Kokkos Task Replay/Replication API



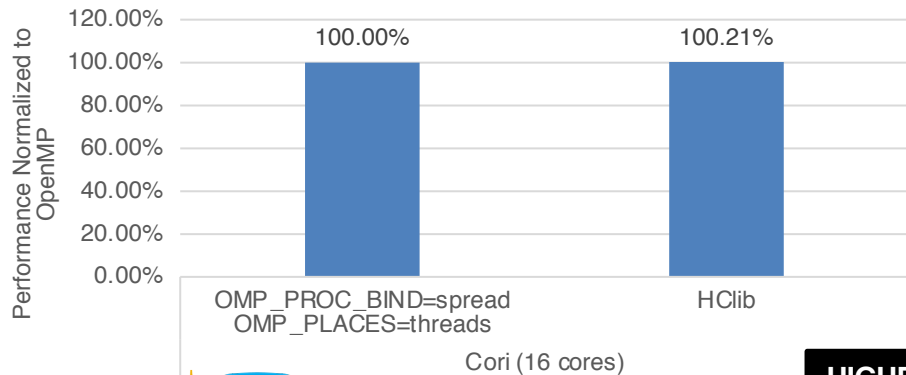
[2] Sri Raj Paul et al. 2019. Enabling Resilience in Asynchronous Many-Task Programming Models. (EuroPar2019)



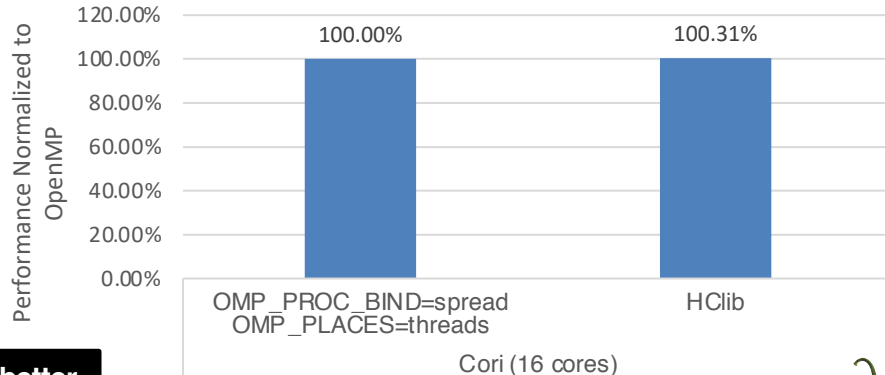
Building Kokkos-HClib backend

- ❑ Non-resilient Execution of miniFE and miniAero of the Mantevo benchmark on Cori@NERSC
- ❑ The HClib backend is comparable to the OpenMP backend

miniFE nx=100, ny=100, nz=100, iterations=200,
no load imbalance (ConjugateGradient)



miniAero nx=128, ny=32, nz=32, iterations=100, no
load imbalance



HIGHER is better



Resilient Kokkos API Design

- ❑ Key Idea: Provide resilient execution spaces

Original `parallel_for`

```
parallel_for(RangePolicy<ExecutionSpace>(0, N), lambda);
```

- ❑ Task Replication

- Semantics: Replicate a task, and check for the equality of output variables

Replicate `parallel_for`

```
parallel_for(RangePolicy<ReplicateSpace>(0, N), lambda);
```

- ❑ Task Replay

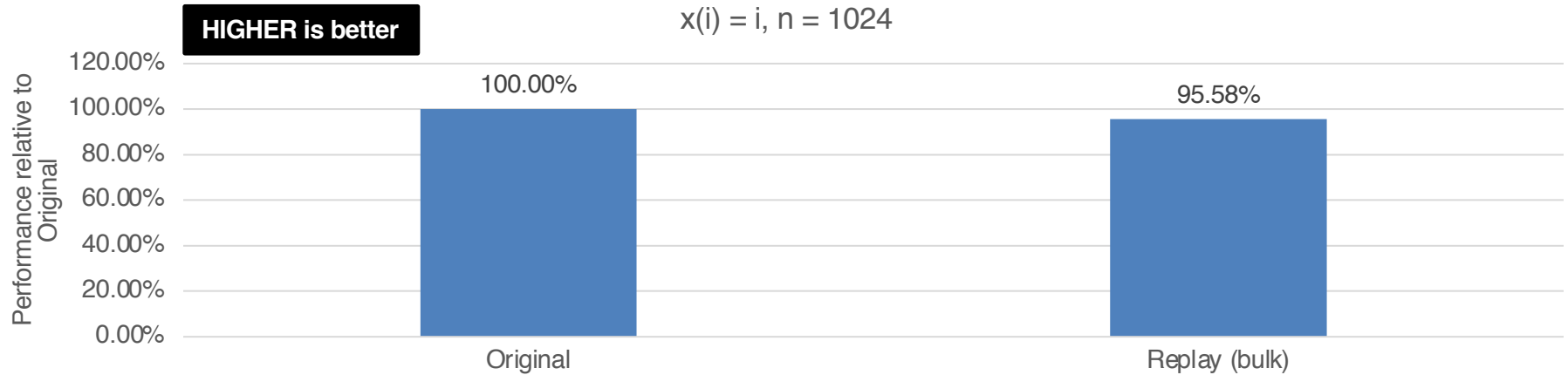
- Semantics: Execute a task, then invoke a user-provided error checking function, and replay the task if the error checking is failed

Replay `parallel_for`

```
parallel_for(RangePolicy<ReplaySpace>(0, N), lambda, lambda_check);
```



Preliminary Performance Evaluation (Overhead of Error Checking)



❑ Variants

- Original: parallel_for only
- Replay (bulk): parallel_for w/ a single error checking (no replay)



Summary & Future Work

□ Summary

- The Kokkos Resilient API enables resiliency in Kokkos in a portable and productive manner
 - ✓ Essentially, the user is only supposed to 1) replace an execution policy with a resilient version and 2) provides an error checking function if necessary
- The developed Kokkos-HClib backend is comparable to existing OpenMP backend for non-resilient execution
 - ✓ Verified with two of the Mantevo benchmark (miniFE/miniAero)

□ Future Work

- Continue the implementation and discuss the performance impact of the Resilient API using different applications
- Support the all the Kokkos constructs in the Kokkos-HClib backend

